# **CMPUT 466** Machine Learning: Day 2 **Professor: Bailey Kacsmar** kacsmar@ualberta.ca Winter 2024

Many of these slides are derived from Alona Fyshe, Alex Thomo. Thanks!

#### More resources...

- From the TAs (thank you TAs)
  - Shalev-Shwartz, S., & Ben-David, S. (2014). Understanding machine learning: From theory to algorithms. Cambridge university press.
  - Bach F. (2023). Learning Theory from First Principle. (https://www.di.ens.fr/~fbach/ltfp\_book.pdf)

## Representing data for ML?

#### Data for ML: A Dataset of a Flower



• Four **features**, plus the **class label** 

ullet



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- Our **task** is to predict class label (flower type) from the 4 features



- Four features, plus the class label
- Our task is to predict class label (flower type) from the 4 features
- To graph these feature vectors, we would need a 4D space
  - Difficult to visualize



## **Dimensions as Features**

- We can use the **dimensions of a vector** to represent the values for different features in our data
  - E.g. the very famous Iris dataset
- In the figure  $\rightarrow$ 
  - X: sepal length
  - Y: sepal width
  - Color of dot: flower type



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- The *Class label* is *discrete*



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• How to represent class label?



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- How to represent class label?
- Unique integer values
  - (e.g. 1=Setosa, 2=Versicolor, 3=Virginica)
- One hot vector
  - [1, 0, 0] -> Setosa
  - [0, 1, 0] -> Versicolor
  - [0, 0, 1] -> Virginica



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#### Some terminology/notation...

## Discrete features

- Class label is an example of a discrete feature
  - As opposed to continuous features like length and width

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  - Favorite movie

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## Discrete features

- Class label is an example of a discrete feature
  - As opposed to continuous features like length and width
- Features can also be discrete
  - E.g. number of petals
  - Favorite movie
- Sometimes these **features** are **ordinal** (they have an **ordering**)
  - Number of petals
  - Not favorite movie

## Discrete features for ML

- When features are **ordinal**, it can make sense to represent them with **integer numbers**
- When features are **categorical** (i.e. non-ordinal) **one hot vectors** work better



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- A vector is a list of numbers
  - The number of dimensions is the **length** of the list

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- A vector is a list of numbers
  - The number of dimensions is the length of the list
- A matrix is a table of numbers, so it has a length and a height
  - E.g. 5x2, 10x100
  - Convention is Rows x Columns (e.g., Roman Catholic, Rock, Roll Call, Rate Class)

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## More Terms/Notation

- A vector is a list of numbers
  - The number of dimensions is the length of the list
- A matrix is a table of numbers, so it has a length and a height
  - E.g. 5x2, 10x100
  - Convention is Rows x Columns
- By this same logic, a vector is actually a matrix with length or height of 1
  - 6x1 is a column vector with 6 elements
  - 1x3 is a row vector with 3 elements

## **Notational Conventions**

• Square brackets to denote boundaries of vectors/matrices

- Convention is for variable names that denote vectors to be
  - Lowercase a
  - Bold or have an arrow over them (not always adhered to if the context makes the form of the variable clear)
- Matrices
  - Uppercase
  - Plain font

- Communicate the size of a matrix like this:  $A \in \mathbb{R}^{n \times p}$
- •

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- The "R" is a symbol for real numbers (i.e. numbers that don't need to be integers)  $\boldsymbol{a} \in \mathbb{R}^p$

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- Communicate the size of a matrix like this:  $A \in \mathbb{R}^{n \times p}$
- The "R" is a symbol for real numbers (i.e. numbers that don't need to be integers)  $\boldsymbol{a} \in \mathbb{R}^p$
- Communicate the size of a vector like this:  $A \in \mathbb{R}^{n \times p}$

- Communicate the size of a matrix like this:  $A \in \mathbb{R}^{n \times p}$
- The "R" is a symbol for real numbers (i.e. numbers that don't need to be integers)  $\boldsymbol{a} \in \mathbb{R}^p$
- Communicate the size of a vector like this:  $A \in \mathbb{R}^{n \times p}$
- Transpose (T) means to swap rows for columns  $A^T \in \mathbb{R}^{p imes n}$

## Example: text documents

- Representing text as a feature vector
- Example (nonsensical) text:

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• D1: brown cat brown cat dog cat mouse

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- D2: brown cat mouse mouse mouse
- D3: dog brown brown cat meow

## Example: text documents

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## Example: text documents

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  - D1: brown cat brown cat dog cat mouse
  - D2: brown cat mouse mouse mouse
  - D3: dog brown brown cat meow
- Identify vocabulary (all words across all documents)
  - brown, cat, dog, mouse, meow (this is the feature order below)
- Features are the # of occurrences of each vocabulary word in doc.

- D2: [1, 1, 0, 3, 0]
- D3: [**2**, **1**, **1**, **0**, **1**]

#### **Vector Addition**



#### v+w: [4, 1]

Pic from <u>youtube playlist</u> video 1

## Vector addition for our text dataset?

- Recall:
  - D1: [2, 3, 1, 1, 0]
    D2: [1, 1, 0, 3, 0]
- What does it mean to have a new document A = D1 + D2?
- I.e. what document would give us a vector equivalent to A = D1 + D2?



## Scalar multiplication for vectors



## Scalar multiplication for vectors



## Scalar multiplication for vectors



#### Scalar multiplication mean for our text dataset?

- Recall:
  - D1: [**2, 3, 1, 1, 0**]
- What does it mean to have document A = 2 \* D1?


### Next: Inner product (dot product)

• Definition 
$$\boldsymbol{a}\cdot \boldsymbol{b} = \sum_i a_i b_i$$

• E.g. 3-D vectors

$$\boldsymbol{a} \cdot \boldsymbol{b} = \sum_{i=1}^{3} a_i b_i$$
$$\boldsymbol{a} \cdot \boldsymbol{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

# Inner product (dot product)

- This ends up being quite important in ML
- Corresponds to the weighted sum
- Many models make predictions using a weighted sum of the feature vector
- Example: price vector multiplied by quantity vector
- Makes a scalar: can be used as a measure of similarity (sometimes)

# Inner product (dot product)

• Neat tricks with the inner product

• One hot vector times feature vector "selects" a particular element from the vector

• Example: a=[0, 1, 0], b=[7, 5, 8]

### Inner product (dot product)

- Vectors can be squared
- E.g. b=[7, 5, 8], b<sup>2</sup> = ?



# Length of a vector (Euclidean Norm)

• Notation ||a||

• Definition 
$$||a|| = \sqrt{a \cdot a}$$

$$=\sqrt{\sum_{i}a_{i}^{2}}$$

• You may have seen this in the Pythagorean theorem (length of the hypotenuse)

• It's often useful to compute the similarity between two vectors



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• Definition one: Euclidean distance



#### • Definition one: Euclidean distance



### Vector similarity: Euclidean Distance

• Euclidean Distance

$$\sqrt{(w-v)^2}$$

# Vector similarity: Euclidean Distance

- Some problems with Euclidean Distance
- Here x and w are more similar than w and v
- Is that what we want?



# Vector Similarity...Cosine Similarity

- Calculate the cosine of the angle between two vectors  $a \cdot b$ 
  - Small angle -> very similar
  - Large angle -> very dissimilar
  - Invariant to length, sensitive to direction



### Matrices

- Can be thought of as a function that transforms space
- In ML, our data is usually formatted into a **matrix**, where the **rows** correspond to **data samples**, and the **columns correspond to the features**



### Matrix Multiplication

- E.g. A \* B
- Each *row* vector of A dot product with each *column* vector of B
  - Again, Roll Call to remember which is rows and which is cols
- Scalar appears in resulting matrix where the row and column intersect
- The # cols of A must match # of rows in B

 $A \in \mathbb{R}^{n \times p}$  $B \in \mathbb{R}^{p \times m}$  $(AB) \in \mathbb{R}^{n \times m}$ 

### Matrix Multiplication



### **Special Matrices**

- Identity matrix (often denoted I)
  - Square matrix, All zeros, except for the diagonal elements are 1

$$\mathbf{I_n} = \underbrace{\left(\begin{array}{ccccc} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & & \ddots & \\ 0 & 0 & 0 & \cdots & 1 \end{array}\right)}_{n \text{ columns}} n \text{ rows}$$

• Called the Identity because IA = A, for all matrices A

# **Special Matrices and Invertible Matrices**

- Inverse of a matrix  $A(A^{-1}) = I$
- Only square matrices are invertible
- Finding the inverse is complex for large matrices
  - We won't worry about it, the computer can do it for us



• Some matrices are not invertible! (Singular) :(

### **Probability Overview**

Many of these slides are derived from Alona Fyshe, Seyong Kim, Tom Mitchell, William Cohen, Eric Xing. Thanks!

# Why do we care about probability?

• Helps us reason about how to make the best decision for cases were we need to generalize:

Temp	Precip	Day	Clothes	
22	None	Fri	Casual	Walk
3	None	Sun	Casual	Walk
10	Rain	Wed	Casual	Walk
30	None	Mon	Casual	Drive
20	None	Sat	Formal	Drive
25	None	Sat	Casual	Drive
-5	Snow	Mon	Casual	Drive
27	None	Tue	Casual	Drive
24	Rain	Mon	Casual	?

# **Recall: Generalization**

#### Dealing with previously unseen cases

• Will she walk or drive?

Temp	Precip	Day	Clothes	
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We might plausibly make any of the following arguments:

- She's going to walk because it's raining today and the only other time it rained, she walked.
- She's going to drive because she has always driven on Mondays...

# Terminology: Random Variables

- Informally, X is a random variable if
  - X denotes something about which we are uncertain
  - perhaps the outcome of a randomized experiment
    - e.g. rolling a die
- Examples
  - X = The hometown of a randomly drawn person from our class
    - multivalued
  - X = True if two randomly drawn persons from our class have same birthday
    - binary

### **Functions of Random Variables**

 Define P(X) as "the fraction of possible worlds in which X is true" or "the fraction of times X holds, in repeated runs of the random experiment"



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- Define P(X) as "the fraction of possible worlds in which X is true" or "the fraction of times X holds, in repeated runs of the random experiment"
  - the set of possible worlds is called the sample space, S



More formally, we have

#### •a sample space S (e.g., set of students in our class)

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  - Height: S 🛛 Real numbers (continuous)
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- an event is a subset of S
  - e.g., the subset of S for which handedness = r
  - e.g., the subset of S for which (handedness=r) AND (eyeColor=blue)

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  - e.g., the subset of S for which handedness = r
  - e.g., the subset of S for which (handedness=r) AND (eyeColor=blue)
- •We are often interested in probabilities of specific events and of specific events conditioned on other specific events

### The Axiom(s) of Probability •Assume binary random variables A and B.

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•Assume binary random variables A and B.

- 0 <= P(A) <= 1
- P(True) = 1
- P(False) = 0
- P(A or B) = P(A) + P(B) P(A and B)

### Visualizing Probability Axioms

Worlds in which A is true

Worlds in which A is False (~A)

### Towards Interpreting the axioms • P(A) = 0



The area of A can't get any smaller than 0

And a zero area would mean no world could ever have A true

P(True) = 0

# Towards Interpreting the axioms P(A) = 1



The area of A can't get any bigger than 1

And an area of 1 would mean all worlds will have A true

P(True) = 1

### Towards Interpreting the Axioms

0 <= P(A) <= 1



#### Towards Interpreting the axioms • P(A or B) = P(A) + P(B)

[WRONG! but why?]





# Towards Interpreting the axioms

• P(A or B) = P(A) + P(B) - P(A and B)





Simple addition and subtraction

### Another useful theorem

$$0 \le P(A) \le 1$$
,  $P(True) = 1$ ,  $P(False) = 0$ ,  
 $P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$ 

$$P(A) = P(A \land B) + P(A \land \ \ B)$$
#### **Elementary Probability in Pictures**

•  $P(A) = P(A \land B) + P(A \land \ \ B)$ 



•  $P(A \text{ or } B) = P(A \land B) + P(A \land B) + P(A \land B)$ 

#### **Extending the Axiom**

• P(A or B or C) = ?





### Multivalued Discrete Random Variables

- Suppose A can take on more than 2 values
- A is a <u>random variable with arity k</u> if it can take on exactly one value out of {v<sub>1</sub>, v<sub>2</sub>, ... v<sub>k</sub>}
- *Example:* A={1,2,3...,20}: good for 20-sided dice games
- Notation: let's write the event AHasValueOfv as "A=v"

$$P(A = v_i \land A = v_j) = 0 \text{ if } i \neq j$$
  
Thus... $P(A = v_1 \lor A = v_2 \lor \ldots \lor A = v_k)$ 

## Elementary Probability in Pictures $\sum_{j=1}^{k} P(A = v_j) = 1$ (Law of total probability)



### **Bunny Break**







## Definition of Conditional Probability P(A ^ B) P(A|B) = -------P(B)**Corollary: The Chain Rule** $P(A \land B) = P(A|B) P(B)$

## Definition of Conditional Probability P(A ^ B) P(A|B) = -------**P(B) Corollary: The Chain Rule** $P(A \land B) = P(A | B) P(B)$ $P(A \wedge B \wedge C) = P(A \mid B \wedge C) P(B \wedge C)$

Definition of Conditional Probability P(A ^ B) P(A|B) = -------P(B)**Corollary: The Chain Rule** 

> $P(A \land B) = P(A|B) P(B)$   $P(A \land B^{\land} C) = P(A|B \land C) P(B \land C)$  $= P(A|B^{\land} C) P(B|C) P(C)$

• Definition: two events A and B are *independent* if: P(A and B)=P(A)\*P(B)

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- Definition: two events A and B are *independent* if: P(A and B)=P(A)\*P(B)
- Intuition: knowing A tells us nothing about the value of B (and vice versa)
- From chain rule

$$P(A \land B) = P(A|B) P(B) = P(A)P(B)$$
  
- >  $P(A|B) = P(A)$ 

• You frequently need to assume the independence of *something* to solve a learning problem.

#### Continuous Random Variables

•The discrete case: sum over all values of A is 1



•The continuous case: infinitely many values for A and the *integral* is 1

 $\int_{-\infty}^{\infty} f_{P}(x) \, dx = 1$ 

*f(x)* is a probability density function (pdf)

 $\forall x, \, f_{P}(x) \geq 0$ 

. . . .

#### Continuous Random Variables

•The discrete case: sum over all values of A is 1

$$\sum_{j=1}^{k} P(A = v_j) = 1$$

•The **continuous case:** infinitely many values for A and the *integral* is 1

 $\int_{-\infty}^{\infty} f_{P}(x) \, dx = 1$ 

f(x) is a probability density function (pdf)

- 1. 0<=P(A) <= 1
- 2. Pr(True) = 1
- 3. P(A or B) = P(A) + P(B) P(A and B)

also

 $\forall x, f_P(x) \ge 0$ 

#### **Bayes Rule**

#### Let's write two expressions for P(A ^ B)



 $P(A \land B) = P(A | B) P(B)$  $P(A \land B) = P(B | A)P(A)$ 

 $P(A \land B) = P(A|B) P(B)$  $P(A \land B) = P(B|A)P(A)$ P(A|B) P(B) = P(B|A)P(A)



Let's write two expressions for P(A ^ B)

#### **Bayes Rule**

 $P(A \land B) = P(A|B) P(B)$  $P(A \land B) = P(B|A)P(A)$ P(A|B) P(B) = P(B|A)P(A)



Let's write two expressions for P(A ^ B)

#### **Bayes Rule**

$$P(A|B) = \frac{P(B|A) * P(A)}{P(B)}$$
Bayes' rule

we call P(A) the "prior"

and P(A|B) the "posterior"



**Bayes, Thomas (1763)** An essay towards solving a problem in the doctrine of chances. *Philosophical Transactions of the Royal Society of London*, **53:370-418** 

...by no means merely a curious speculation in the doctrine of chances, but necessary to be solved in order to a sure foundation for all our reasonings concerning past facts, and what is likely to be hereafter.... necessary to be considered by any that would give a clear account of the strength of *analogical* or *inductive reasoning*...

## Other Forms of Bayes Rule $P(A | B) = \frac{P(B | A)P(A)}{P(B | A)P(A) + P(B | \sim A)P(\sim A)}$

$$P(A | B \land X) = \frac{P(B | A \land X)P(A \land X)}{P(B \land X)}$$

#### **Applying Bayes Rule**

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B \mid A)P(A) + P(B \mid \sim A)P(\sim A)}$$

A = you have the flu, B = you just coughed

Assume: P(A) = 0.05

#### **Applying Bayes Rule**

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B \mid A)P(A) + P(B \mid \sim A)P(\sim A)}$$

A = you have the flu, B = you just coughed

Assume: P(A) = 0.05

Also assume the following information is known to you P(B|A) = 0.80 $P(B| \sim A) = 0.4$ 

what is P(flu | cough) = P(A|B)?



#### **Next! Joint distribution**

• Probability of >1 thing happening at the same time

- Probability it will rain today and I forgot my umbrella
  - P(rain=true,umbrella=false)



#### Example: Boolean variables A, B, C

Recipe for making a joint distribution of M variables:

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 Make a truth table listing all combinations of values of your variables (if there are M Boolean variables then the table will have 2<sup>M</sup> rows).

#### Example: Boolean variables A, B, C

Α	В	C
0	0	0
0	0	1
0	1	0
0	1	1
1	0	0
1	0	1
1	1	0
1	1	1

Recipe for making a joint distribution of M variables:

- Make a truth table listing all combinations of values of your variables (if there are M Boolean variables then the table will have 2<sup>M</sup> rows).
- 2. For each combination of values, say how probable it is.

#### Example: Boolean variables A, B, C

Α	В	C	Prob
0	0	0	0.30
0	0	1	0.05
0	1	0	0.10
0	1	1	0.05
1	0	0	0.05
1	0	1	0.10
1	1	0	0.25
1	1	1	0.10

Recipe for making a joint distribution of M variables:

- Make a truth table listing all combinations of values of your variables (if there are M Boolean variables then the table will have 2<sup>M</sup> rows).
- 2. For each combination of values, say how probable it is.
- 3. If you **subscribe to the axioms of probability**, those numbers **must sum to 1**.

What goes here?

#### Example: Boolean variables A, B, C

0.05

0.25

B

0.30

Α	В	C	Prob
0	0	0	0.30
0	0	1	0.05
0	1	0	0.10
0	1	1	0.05
1	0	0	0.05
1	0	1	0.10
1	1	0	0.25
1	1	1	0.10

 $0.10^{\circ}$ 

99

0.05

0.05

#### Joint Probability Distribution



Once you have the joint distribution, you can **ask for the probability** of **any logical expression** involving your attribute



# Using the Joint Distribution



P(Poor) = 0.7604

 $P(E) = \sum P(\text{row})$ 

rows matching E

# Using the Joint Distribution

gender	hours_worked	wealth	
Female	v0:40.5-	poor	0.253122
		rich	0.0245895
$\subset$	v1:40.5+	poor	0.0421768
		rich	0.0116293
Male	v0:40.5-	poor	0.331313
		rich	0.0971295
	v1:40.5+	poor	0.134106
		rich	0.105933

P(Poor) = 0.7604

 $P(E) = \sum P(\text{row})$ rows matching E

# Inference with the Joint



$$P(E_1 | E_2) = \frac{P(E_1 \land E_2)}{P(E_2)} = \frac{\sum_{\text{rows matching } E_1 \text{ and } E_2}}{\sum_{\text{rows matching } E_2}}$$

#### Next! Maximum Likelihood Estimation (MLE)

## **Rich vs Poor**

What is the probability of a person being rich, given you know nothing else about that person?







## Let's say 3/5?

We assume that the wealth of the people in our dataset *D* is independently distributed

- $\theta$  = Probability of being rich = P(rich)
  - ? = Probability of being poor = P(poor)

### Let's say 3/5?

We assume that the wealth of the people in our dataset *D* is

independently distributed  $\theta$  = Probability of being rich = P(rich) ? = Probability of being poor = P(poor) D = { r, p, r, r, p}  $\alpha_r$  = # rich  $\alpha_p$ = # poor P(D) = P(r and p and r and r and p)

### Let's say 3/5?

We assume that the wealth of the people in our dataset *D* is

independently distributed  $\theta$  = Probability of being rich = P(rich) ? = Probability of being poor = P(poor)  $D = \{r, p, r, r, p\}$   $\alpha_r = \# rich$   $\alpha_{p} = \# poor$ P(D) = P(r and p and r and r and p)=P(rich) \* P(poor) \* P(rich) \*P(rich) \* P(poor)
### Let's say 3/5?

We assume that the wealth of the people in our dataset D is

independently distributed  $\theta$  = Probability of being rich = P(rich) ? = Probability of being poor = P(poor)  $D = \{r, p, r, r, p\}$   $\alpha_r = \# rich$   $\alpha_{p} = \# poor$ P(D) = P(r and p and r and r and p)=P(rich) \* P(poor) \* P(rich) \*P(rich) \* P(poor) $=\theta * (1 - \theta) * \theta * \theta * (1 - \theta)$  $=(1-\theta)^{\alpha_p}*\theta^{\alpha_r}$ 

### Let's say 3/5?

We assume that the wealth of the people in our dataset *D* is

independently distributed  $\theta$  = Probability of being rich = P(rich) ? = Probability of being poor = P(poor) $D = \{r, p, r, r, p\}$   $\alpha_r = \# rich$   $\alpha_{p} = \# poor$ P(D) = P(r and p and r and r and p)=P(rich) \* P(poor) \* P(rich) \* $\theta$   $\alpha F * \theta$ P(rich) \* P(poor) $= \theta * (1 - \theta) * \theta * \theta * (1 - \theta)$  $= (1 - \theta)^{\alpha_p} * \theta^{\alpha_r} \quad \text{argmax } P$ 110

# That's Maximum Likelihood Estimation (MLE)

It's not always the best solution...

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Collect some data (20 rolls)
 Estimate P(i)=CountOf(rolls of i)/CountOf(any roll)

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But: Do I really think it's *impossible* to roll a 1,2 or 3?

## A better solution?

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## A better solution

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0. *Imagine* some data (20 rolls, each i shows up 1x)
1. Collect some data (20 rolls)
2. Estimate P(i)

## A better solution?



$$\hat{P}(i) = \frac{CountOf(i) + 1}{CountOf(ANY) + CountOf(IMAGINED)}$$

P(1)=1/40P(2)=1/40P(3)=1/40P(4)=(2+1)/40. . . P(19)=(5+1)/40P(20)=(4+1)/40=1/8

0.2 vs. 0.125 – really different! Maybe I should "imagine" less data?

# What if we know that poor people are much more common than rich people?





















## We have a belief about $\, heta$

## • $P(\theta | D) = P(D | \theta) * P(\theta) / P(D)$

# Now we can incorporate our belief about $\theta$

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 $\mathbf{X}$ 

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## $\propto$ P(D| $\theta$ )\*P( $\theta$ )

## Now we can incorporate our belief about $\theta$

This is a MAP (Maximum A Posteriori) Estimate

#### **Conjugate Prior**

- Our likelihood so far has been based on a Bernoulli distribution.
- Beta is a conjugate prior to Bernoulli
  - This means their pdfs (probability density functions) play nice together
  - P(D|θ)\*P(θ) will be easy to deal with
  - Called the posterior likelihood

#### **Estimating Parameters**

- Maximum Likelihood Estimate (MLE): choose  $\theta$  that maximizes probability of observed data  $\hat{\theta} = \arg \max_{\theta} P(\mathcal{D} \mid \theta)$
- Maximum a Posteriori (MAP) estimate: choose  $\theta$ that is most probable given **prior probability and the data**  $\hat{\theta} = \arg \max_{\theta} P(\theta \mid D)$  $= \arg \max_{\theta} = \frac{P(D \mid \theta)P(\theta)}{P(D)}$

A tutorial:

http://www.cs.ubc.ca/~murphyk/Teaching/CS340-Fall06/reading/bernoulli.pdf

#### Thanks, see you Tuesday!

